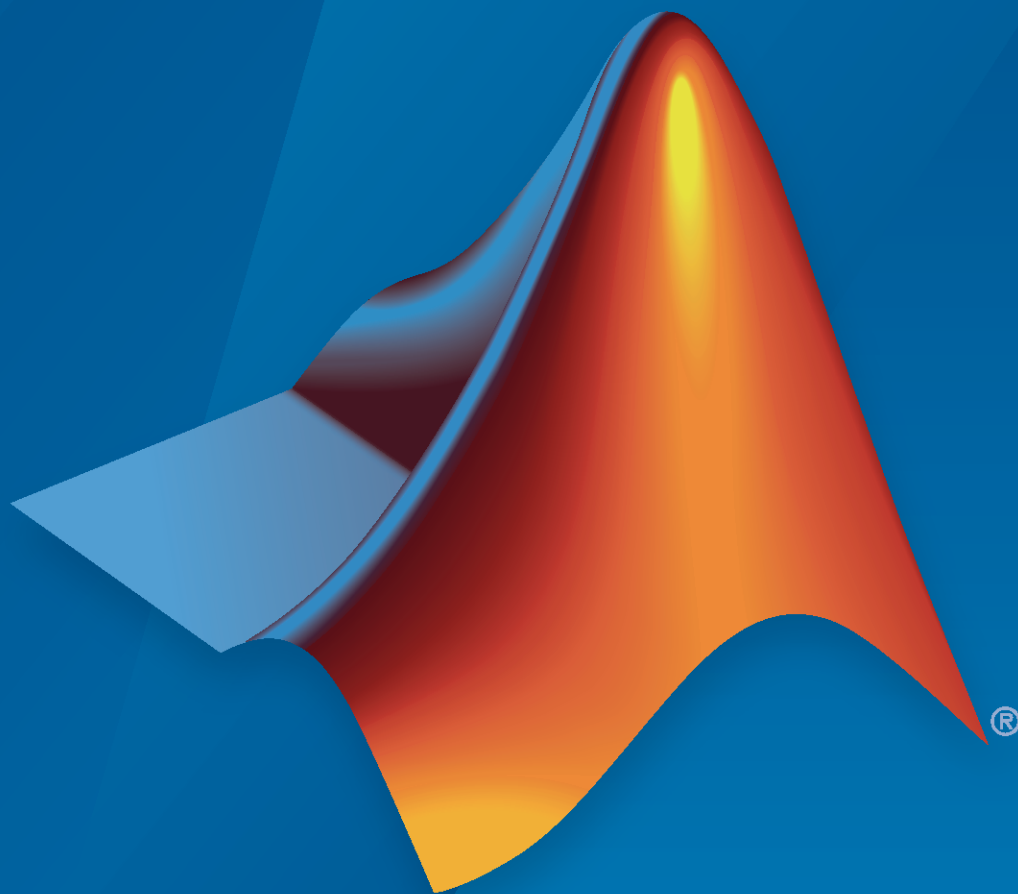


ROS Toolbox

Getting Started Guide



MATLAB® & SIMULINK®

R2022b



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Revision History

September 2019	Online only	New for Version 1.0 (R2019b)
March 2020	Online only	Revised for Version 1.1 (R2020a)
September 2020	Online only	Revised for Version 1.2 (R2020b)
March 2021	Online only	Revised for Version 1.3 (R2021a)
September 2021	Online only	Revised for Version 1.4 (R2021b)
March 2022	Online only	Revised for Version 1.5 (R2022a)
September 2022	Online only	Revised for Version 1.6 (R2022b)

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Product Overview

ROS Toolbox Product Description

Design, simulate, and deploy ROS-based applications

ROS Toolbox provides an interface connecting MATLAB® and Simulink® with the Robot Operating System (ROS and ROS 2), enabling you to create a network of ROS nodes. The toolbox includes MATLAB functions and Simulink blocks to import, analyze, and play back ROS data recorded in rosbag files. You can also connect to a live ROS network to access ROS messages.

The toolbox lets you verify ROS nodes via desktop simulation and by connecting to external robot simulators such as Gazebo. ROS Toolbox supports C++ code generation (with Simulink Coder™), enabling you to automatically generate ROS nodes from a Simulink model and deploy to simulated or physical hardware. Support for Simulink external mode lets you view messages and change parameters while your model is running on hardware.